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10.2-1 Simulink solution of 10.2-2 Exporting to the MATLAB workspace 10.2-3 Simulink model for 10.3-1 Simulink model of a two-mass suspension system 10.4-1 Simulink model of a rocket-propelled sled 10.4-2 Model of a relay-controlled motor 10.5-1 Response with a dead zone 10.6-1 Model of a nonlinear pendulum Chapter Eleven

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A strong solver based on a hierarchical adaptive nonlinear iterative method (HANIM) has been implemented for primal flow computations aiming to improve the robustness and efficiency of the standard preconditioner-alone solver. Please see the User Manual for usage of the HANIM solver.

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The amplitude of a wave may be constant (in which case the wave is a c.w. or continuous wave), or may be modulated so as to vary with time and/or position. The outline of the variation in amplitude is called the envelope of the wave. Mathematically, the modulated wave can be written in the form:  $(, ) = (, ) (+),$  where  $(, )$  is the amplitude envelope of the wave,  $(, )$  is the wavenumber and  $(, )$  is the phase.

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